



# Next-Generation Non-Surgical Neurotechnology (N<sup>3</sup>)



## N<sup>3</sup> Proposer's Day

Dr. Al Emondi



# Next generation approach to brain interfaces



**DOD Problem:** Able-bodied military personnel cannot use current neural interfaces



**Goal:**  
**Create reliable neural interfaces without  
the need for surgery or implanted  
electrodes**

*Facilitate multitasking at the speed of thought*

*Interface with smart decision aids*



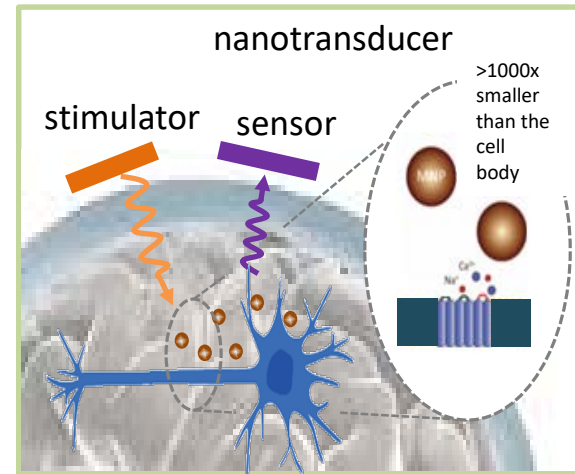
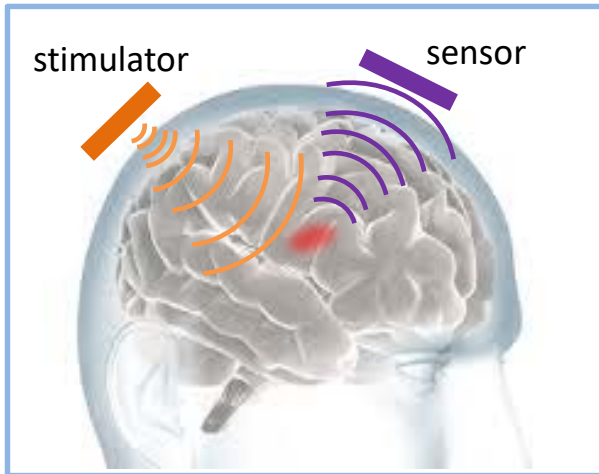
# Two Technical Areas



	TA1: Noninvasive
Invasiveness	External device
Example Technology	Ultrasound, light, RF, magnetic fields
Signal Quality	Neural ensemble activity



TA2: Minutely Invasive
Injectable/ingestible/intranasal
Nanotechnology, membrane modifications, molecular assembly
Single neuron activity





# TA1: Completely Noninvasive Neural Interfaces



**Objective:** Create a noninvasive read/write system

## PHASE I

Develop subcomponent technology

### Develop systems level design

link margin power budgets, channelization approaches

### Fabricate subcomponents

circuits, sensor, emitter, hardware

### Characterize subcomponents

resolution and latency performance

### Assess scattering and attenuation

compare to systems level design parameters

### Demonstrate read and write

through "skull and tissue like" mediums

*Bench top demo*

## PHASE II

Integrate and validate *in vivo*

### Integrate subcomponents

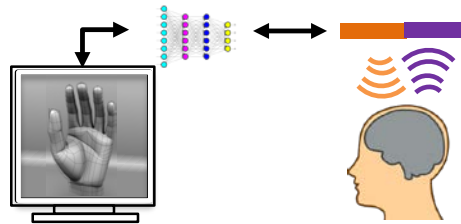
combine multiple read and write subcomponents into one device

### Evaluate physical properties

crosstalk, SNR, and safety parameters of integrated device *in vivo*

### Develop algorithms

decode neural ensemble activity and encode sensory feedback to the brain



*In vivo proof of concept*

## PHASE III

Refine and demonstrate

### Characterize refined system

meet metrics for bidirectional system

### Refine algorithms

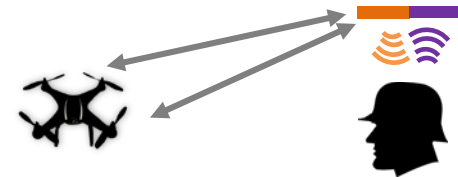
achieve lower system latency

### Demonstrate system capabilities

decode motor and cognitive signals, and encode sensory feedback

### Design DoD relevant final demo

ex. simultaneously perform multiple tasks



*In field proof of concept*

**Deliverable:** Human demonstration of closed loop prototype system in a DoD relevant task



# TA1: Noninvasive metrics



## Phase I

### Read and Write Subcomponents

**Spatial resolution**

<1 mm<sup>3</sup>

**Temporal resolution**

<10 ms

**Stability**

continuous operation for ≥ 2 hrs

**Accuracy (read/write)**

correlation to ground truth  
accuracy ≥ 95%

## Phase II

### Integrated Device

**Safety**

≤ 1°C rise in tissue volume being read  
from/written to

**Closed loop system latency**

< 100 ms

**Control signals**

≥ 3 DOF

**Sensory signals**

≥ 3 categories  
(ex: detection, alarm)

**Integrated device size**

≤ 125 cm<sup>3</sup>

**Channel count**

read channels/volume (≥16/16mm<sup>3</sup>)  
write channels/volume (≥16/16mm<sup>3</sup>)

## Phase III

### Final System

**Closed loop system latency**

< 50 ms

**Control signals**

≥ 6 DOF

**Sensory signals**

≥ 6 categories

**Multifocal capability**

≥ 4 read/write locations without crosstalk



# TA2: Minutely Invasive Neural Interfaces



**Objective:** Create a minutely invasive read/write system

## PHASE I

Develop subcomponents and nanotransducers

### Develop system level design

nanotransducer and sensor/stimulator

### Fabricate subcomponents

**circuits, hardware and nanotransducer**  
(particle, genetic component, encapsulation material)

### Characterize nanotransducer

cell type specificity at single neuron resolution

### Demonstrate system interaction

sensor/stimulator ↔ nanotransducer



*In vitro demo*

## PHASE II

Integrate and validate *in vivo*

### Integrate subcomponents

combine multiple read and write subcomponents into one device

### Evaluate physical properties

crossstalk, SNR, specificity of sensor/stimulator  
toxicity and stability of nanotransducer

### Develop algorithms

decode and encode from/to single neurons

### Identify patient population

prepare for clinical proof of concept

### Optimize peripheral delivery route

cross the BBB targeting specific neurons

*Preclinical proof of concept*

## PHASE III

Refine and demonstrate

### Characterize refined system

bidirectional system and interaction with nanotransducer

### Refine algorithms

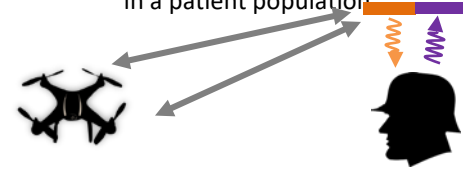
achieve lower system latency

### Demonstrate system capabilities

decode motor and cognitive signals, and encode sensory feedback

### Design DoD relevant final demo

in a patient population



*Clinical proof of concept*

**Deliverable:** High spatiotemporal resolution bidirectional system demonstrated in animal and human.



# TA2: Minutely Invasive Metrics



## Phase I

### Subcomponents and Transducers

**Spatial resolution**  
<50  $\mu\text{m}^3$

**Temporal resolution**  
<10 ms

**Stability**  
Continuous operation for  $\geq 2$  hrs

**Accuracy (read/write)**  
Correlation to ground truth  
accuracy  $\geq 95\%$

**Cell type specificity**  
Excitatory/inhibitory control for stimulation

**Delivery**  
Viable strategy identified

## Phase II

### Integrated Device

**Safety**  
 $\leq 1^\circ\text{C}$  rise in tissue volume being read  
from/written to

**Closed loop system latency**  
< 100 ms

**Control signals**  
 $\geq 5$  DOF

**Sensory signals**  
 $\geq 5$  categories  
(ex: detection, alarm)

**Integrated device size**  
 $\leq 125 \text{ cm}^3$

**Channel count**  
read channels/volume ( $\geq 16/16\text{mm}^3$ )  
write channels/volume ( $\geq 16/16\text{mm}^3$ )

## Phase III

### Final System

**Closed loop system latency**  
< 50 ms

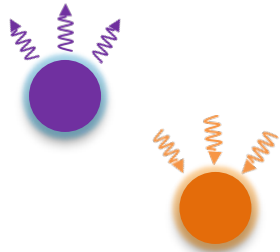
**Control signals**  
 $\geq 10$  DOF

**Sensory signals**  
 $\geq 10$  categories

**Multifocal capability**  
 $\geq 4$  read/write locations without crosstalk



# N<sup>3</sup> Notional System

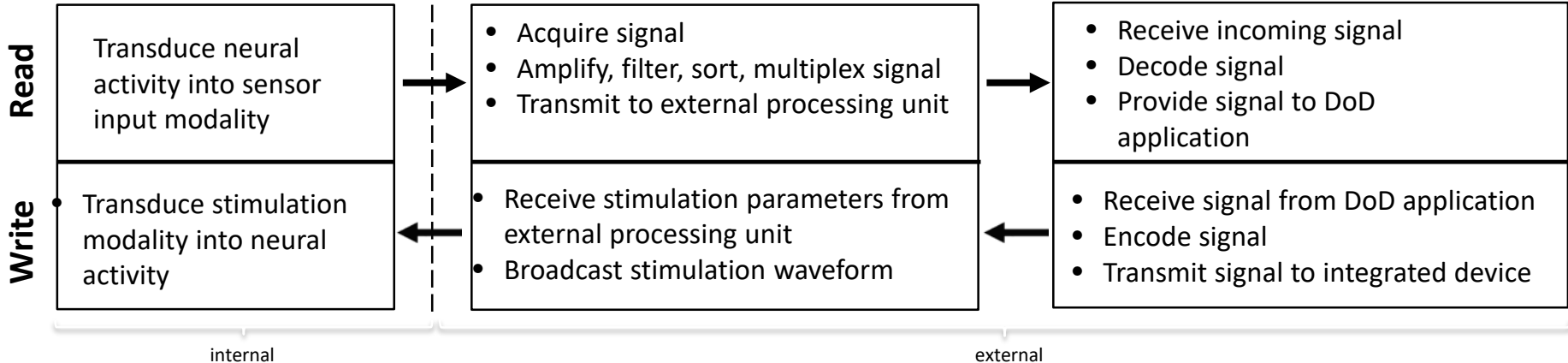


## Nanotransducer

(TA2 only)

## Integrated Device

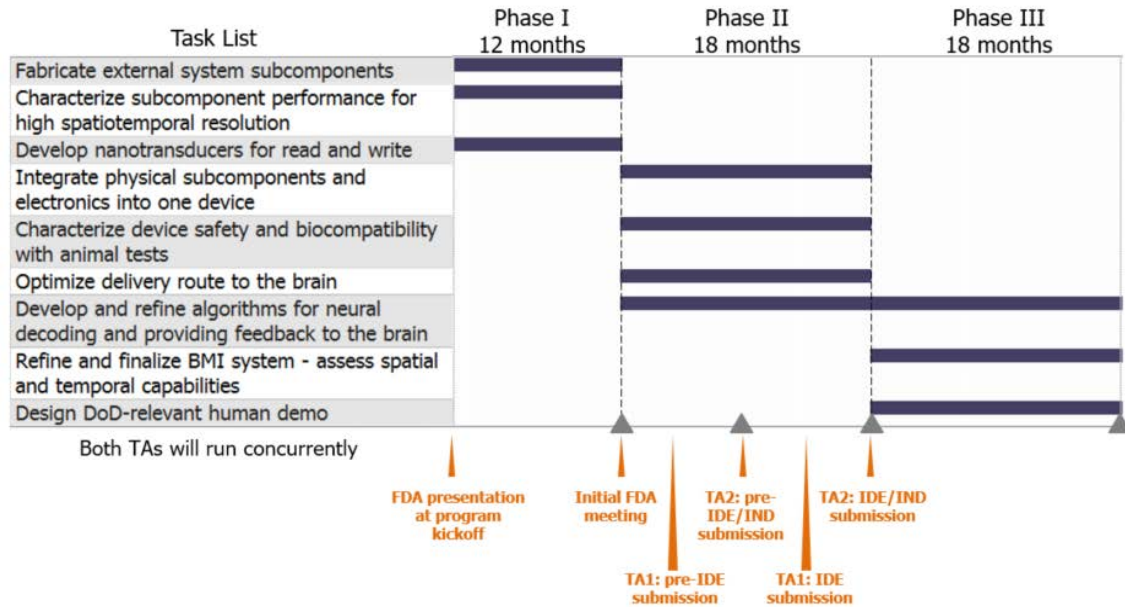
## Processing Unit







# N<sup>3</sup> program structure and milestones



## Program demos



**12 Mo.** Benchtop independent read and write capabilities

**21 Mo.** *In vivo* (animals, humans) open loop read and write capabilities

**30 Mo.** Demo: *In vivo* (animals, humans) closed-loop of integrated read and write capabilities

**48 Mo.** Demo: DoD relevant task with closed-loop control and feedback in humans



# Technical Descriptions to Include in the Proposal



## 1. Fabrication description for subcomponents (TA1 and TA2) and nanotransducer (TA2)

- Provide a detailed development timeline that describes relevant microfabrication or nanofabrication processes

## 2. System-level design descriptions

- Describe the components, and a strategy for identifying system parameters
- Describe the underlying physics, how to overcome scattering/attenuation challenges

## 3. Phase I, II, III demonstration descriptions

- Describe demonstration ideas, justify the chosen method and why it is DoD relevant

## 4. System integration description

- Identify a system integrator, and describe how to integrate read/write subcomponents

## 5. Safety and histology description

- Describe procedures to collect the appropriate safety and histology data for FDA approval and to meet N<sup>3</sup> metrics

## 6. Security Measures

- Describe approaches to ensure confidentiality, integrity, and availability to prevent spoofing, tampering, or denial of system

## 7. Ethical, Legal, and Societal Implications (ELSI)

- Address the potential ELSI implications of the proposed technology



# Teaming



## To fully address the BAA you will likely need to team with other entities

- You must find your collaborators on your own
- Your team should submit a unified proposal under a single PI
- This BAA is open to educational institutions, government labs, and/or private companies
- Foreign entities may join a team or submit as the PI
- If you are a member of a team, you may join any number of other teams or form your own and submit a proposal as PI
- Note that the cost volume for each team member must be at the same level of details as for the PI



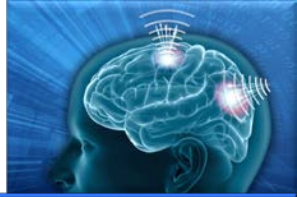
# Additional Advice



- Read the BAA and follow all instructions carefully
- A successful proposal addresses all aspects of the BAA
- Pay attention to “must” and “should” language in the BAA
- Do not submit work that is not applicable to the BAA
- Do not propose to do anything that is not directly relevant to the BAA
- Do not propose incremental improvements to existing technology
- Do not submit an irrelevant or incomplete proposal in the hope we’ll fund it anyway
- Submitting a proposal abstract is **highly recommended**



## Final Bits of Advice



**Teaming is very important!**  
**Use today to network and team**